Spectrum of Output in State Space Model

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1 PROBLEM STATEMENT

The state space model of a system is defined as

$$\begin{aligned} x(t+1) &= Fx(t) + v(t), \\ y(t) &= Hx(t) + e(t). \end{aligned}$$
 (1.1)

where v(t) and e(t) are complex-valued uncorrelated sequences with zero mean and

$$\mathbf{E} \begin{pmatrix} \nu(t) \\ e(t) \end{pmatrix} (\nu^*(s) \ e^*(s)) = \begin{pmatrix} R_1 & R_{12} \\ R_{21} & R_2 \end{pmatrix} \delta_{t,s}.$$
 (1.2)

According to [1], after reaching stationary state, the mean of x(t) and y(t) are both 0, namely $m_x = 0$ and $m_y = 0$. The covariance of x(t), namely $R_x(t, t)$, denoted as *P*, is given as

$$P = \sum_{j=0}^{\infty} F^j R_1 F^{*j}.$$
 (1.3)

By Eqs. (4.20) and (4.21) in [1], after reaching stationary state the output covariance function is given as

$$R_{\nu}(t, t) = HPH^* + R_2, \tag{1.4}$$

$$R_{\gamma}(t+\tau, t) = HF^{\tau}PH^{*} + HF^{\tau-1}R_{12}, \tau > 0$$
(1.5)

$$R_{\nu}(t-\tau, t) = HPF^{*\tau}H^{*} + R_{21}F^{*(\tau-1)}H^{*}, \tau > 0$$
(1.6)

The spectrum of a time series, say $\{y(t)\}$, is defined as

$$\phi_{y}(z) = \sum_{n=-\infty}^{\infty} R_{y}(t+n, t) z^{-n}.$$
(1.7)

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By [1], in the stationary case, the spectrum of y(t) is given as

$$\phi_{y}(z) = H(zI - F)^{-1}R_{1}(z^{-*}I - F)^{-*}H^{*} + R_{2}$$
$$H(zI - F)^{-1}R_{12} + R_{21}(z^{-*}I - F)^{-*}H^{*}, \qquad (1.8)$$

which is calculated via the *transfer function model* rather than state space model. Elaborate that the same result can also be given via the state space model.

2 ELABORATION

Take Eqs. (1.4), (1.5) and (1.6) into Eq. (1.7), we obtain

$$\phi_{y}(z) = HPH^{*} + R_{2} + \sum_{n=1}^{\infty} (HF^{n}PH^{*} + HF^{n-1}R_{12})z^{-n} + \sum_{m=1}^{\infty} (HPF^{*m}H^{*} + R_{21}F^{*(m-1)}H^{*})z^{m},$$
(2.1)

which can be rewritten as

$$\phi_{y}(z) = HPH^{*} + R_{2} + H(\sum_{n=1}^{\infty} F^{n} z^{-n})PH^{*} + H(\sum_{n=1}^{\infty} F^{n-1} z^{-n})R_{12} + HP(\sum_{m=1}^{\infty} F^{*m} z^{m})H^{*} + R_{21}(\sum_{m=1}^{\infty} F^{*(m-1)} z^{m})H^{*}.$$
(2.2)

First of all, we take care of $\sum F^n z^{-n}$.

$$S_n = \sum_{n=1}^{\infty} F^n z^{-n} \Longrightarrow S_n = \sum_{n=1}^{\infty} (Fz^{-1})^n \Longrightarrow (I - Fz^{-1}) S_n = Fz^{-1} \Longrightarrow (zI - F) S_n = F$$

Therefore,

$$\sum_{n=1}^{\infty} F^n z^{-n} = (zI - F)^{-1} F$$
(2.3)

$$\sum_{n=1}^{\infty} F^{(n-1)} z^{-n} = \left(\sum_{n=1}^{\infty} F^n z^{-n}\right) F^{-1} = (zI - F)^{-1}$$
(2.4)

Similarly,

$$\sum_{n=0}^{\infty} F^n z^{-n} = (zI - F)^{-1} z.$$
(2.5)

Then for $\sum F^{*m}z^m$, we calculate $\sum F^mz^{*m}$ instead in order to follow the notation used in [1]

$$S_m^* = \sum_{m=1}^{\infty} F^m z^{*m} \Longrightarrow S_m^* = \sum_{m=1}^{\infty} (Fz^*)^m \Longrightarrow (I - Fz^*) S_m^* = Fz^* \Longrightarrow (z^{-*}I - F) S_m^* = F$$
$$\Longrightarrow S_m^* = (z^{-*}I - F)^{-1}F$$

Therefore,

$$\sum_{m=1}^{\infty} F^{*m} z^m = F^* (z^{-*} I - F)^{-*}$$
(2.6)

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$$\sum_{m=1}^{\infty} F^{*(m-1)} z^m = F^{-*} (\sum_{m=1}^{\infty} F^{*m} z^m) = (z^{-*} I - F)^{-*}$$
(2.7)

Similarly,

$$\sum_{m=0}^{\infty} F^{*m} z^m = (z^{-*}I - F)^{-*} z^{-1}$$
(2.8)

Remark. Since $(zI - F)^{-1}$ is the sum of Fz, so $(zI - F)^{-1}$ and F can commute, namely $(zI - F)^{-1}F = F(zI - F)^{-1}$. So do $(z^{-*}I - F)^{-*}$ and F^* . Besides, by the different approaches of calculating $\sum F^{*m}z^m$, we know $(z^{-*}I - F)^{-*} = (z^{-1}I - F^*)^{-1}$.

Take Eqs. (2.4) and (2.7) into Eq. (2.2), we get

$$\phi_{y}(z) = H(\sum_{n=1}^{\infty} F^{n} z^{-n} P + P + P \sum_{m=1}^{\infty} F^{*m} z^{m}) H^{*} + R_{2} + H(zI - F)^{-1} R_{12} + R_{21} (z^{-*}I - F)^{-*} H^{*},$$
(2.9)

which is one step closer to Eq. (1.8). Now only the first three terms in Eq. (2.9) need to be handled. Denote HTH^* as the sum of those terms, namely

$$T = \sum_{n=1}^{\infty} F^n z^{-n} P + P + P \sum_{m=1}^{\infty} F^{*m} z^m.$$
 (2.10)

Take Eq. (1.3) into Eq. (2.10) and change the order of sum operator, we get

$$T = \sum_{j=0}^{\infty} \sum_{n=1}^{\infty} F^n z^{-n} F^j R_1 F^{*j} + \sum_{j=0}^{\infty} F^j R_1 F^{*j} + \sum_{j=0}^{\infty} \sum_{m=1}^{\infty} F^j R_1 F^{*j} F^{*m} z^m.$$
(2.11)

Denote the first term in Eq. (2.11) T_f and the sum of the rest two terms as T_b . So $T = T_f + T_b$. Then we have

$$T_f = \sum_{j=0}^{\infty} \sum_{n=1}^{\infty} F^n z^{-n} F^j z^{-j} R_1 F^{*j} z^j = \sum_{j=0}^{\infty} (\sum_{n=j+1}^{\infty} (Fz^{-1})^n) R_1 (F^*z)^j.$$
(2.12)

For T_b , we change the order of sum operator to arrange it as

$$T_{b} = \sum_{j=0}^{\infty} (Fz^{-1})^{j} R_{1} (F^{*}z)^{j} + \sum_{j=0}^{\infty} ((Fz^{-1})^{j} R_{1} \sum_{m=j+1}^{\infty} (F^{*}z)^{m})$$

$$= \sum_{j=0}^{\infty} (Fz^{-1})^{j} R_{1} (F^{*}z)^{j} + \sum_{m=1}^{\infty} (\sum_{j=0}^{m-1} (Fz^{-1})^{j}) R_{1} (F^{*}z)^{m}.$$
 (2.13)

We change the subscripts in the first sum of Eq. (2.13) from *j* to *m* and split the case when m = 0, then

$$T_{b} = (Fz^{-1})^{0}R_{1}(F^{*}z)^{0} + \sum_{m=1}^{\infty} (Fz^{-1})^{m}R_{1}(F^{*}z)^{m} + \sum_{m=1}^{\infty} (\sum_{j=0}^{m-1} (Fz^{-1})^{j})R_{1}(F^{*}z)^{m}$$
$$= (Fz^{-1})^{0}R_{1}(F^{*}z)^{0} + \sum_{m=1}^{\infty} (\sum_{j=0}^{m} (Fz^{-1})^{j})R_{1}(F^{*}z)^{m}$$
$$= \sum_{m=0}^{\infty} (\sum_{j=0}^{m} (Fz^{-1})^{j})R_{1}(F^{*}z)^{m}$$
(2.14)

Again we change the subscripts in the sums of Eqs. (2.12) and (2.14). Use k for the outer sum and l for the inner sum, then

$$T = \sum_{k=0}^{\infty} \left(\sum_{l=k+1}^{\infty} (Fz^{-1})^{l}\right) R_{1}(F^{*}z)^{k} + \sum_{k=0}^{\infty} \left(\sum_{l=0}^{k} (Fz^{-1})^{l}\right) R_{1}(F^{*}z)^{k}$$

$$= \sum_{k=0}^{\infty} \left(\sum_{l=0}^{\infty} (Fz^{-1})^{l}\right) R_{1}(F^{*}z)^{k}$$

$$= \sum_{l=0}^{\infty} (Fz^{-1})^{l} R_{1} \sum_{k=0}^{\infty} (F^{*}z)^{k}.$$
 (2.15)

Take Eqs. (2.5) and (2.8) into Eq. (2.15), we have

$$T = (zI - F)^{-1} zR_1 (z^{-*}I - F)^{-*} z^{-1}$$

= $(zI - F)^{-1} R_1 (z^{-*}I - F)^{-*}$ (2.16)

which conclude the proof.

REFERENCES

[1] Torsten Söderström, *Discrete-time stochastic systems: Estimation and control*, Springer & Verlag, 2002.